

Gauss - Jordan Method to find  $A^{-1}$

\* If a matrix  $A$  is non-singular (invertible), we can make it diagonal using elementary matrices and permutation matrices. For example

$$E_4 P_2 E_3 P_1 E_2 E_1 A = D = \begin{bmatrix} d_1 & & \\ & d_2 & \\ & & \dots \\ & & & d_n \end{bmatrix}$$

Then,

$$D^{-1} E_4 P_2 E_3 P_1 E_2 E_1 A = I.$$

Therefore

$$A^{-1} = D^{-1} E_4 P_2 E_3 P_1 E_2 E_1.$$

If we start the forward elimination with

$$[A \ I],$$

the result is

$$D^{-1} E_4 P_2 E_3 P_1 E_2 E_1 [A \ I]$$

$$= [I \ A^{-1}].$$

To summarize, carry out the elimination

with  $[A \ I]$  to make the identity in the left side, i.e.,  $[I \ B]$ .

Then  $B$  is the inverse of  $A$ .

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Example 1)  $A = \begin{bmatrix} 1 & 1 & 1 \\ 4 & -6 & 0 \\ -1 & 7 & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 4 & -6 & 0 & 1 & 0 \\ -1 & 7 & 1 & 0 & 0 \end{bmatrix} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \end{matrix}$$

$$\Downarrow \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & 1 & 0 \\ 0 & 8 & 3 & 1 & 0 \end{bmatrix} \begin{matrix} \textcircled{2} - 1 \times \textcircled{1} \\ \textcircled{3} + \textcircled{1} \end{matrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & 0 & \frac{3}{8} & 1 \\ 0 & -8 & -2 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 \end{bmatrix} \begin{matrix} \textcircled{1} + \frac{3}{8} \times \textcircled{2} \\ \textcircled{2} + \textcircled{3} \end{matrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & -8 & 0 & -1 & 1 \\ 0 & 0 & 1 & -1 & 1 \end{bmatrix} \begin{matrix} \textcircled{1} - \frac{3}{8} \times \textcircled{3} \\ \textcircled{2} + 2 \times \textcircled{3} \end{matrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & -\frac{5}{8} & -\frac{3}{8} \\ 0 & 0 & 1 & -1 & 1 \end{bmatrix} \begin{matrix} \textcircled{1} \times 2 \\ \textcircled{2} \times -\frac{1}{8} \end{matrix}$$

$$\therefore A^{-1} = \begin{bmatrix} \frac{3}{8} & -\frac{3}{8} & 1 \\ \frac{1}{8} & -\frac{5}{8} & -\frac{3}{8} \\ -1 & -1 & 1 \end{bmatrix}$$

### Inverses

A matrix  $A$  is invertible if there exists  $B$  such that  $BA=I$  and  $AB=I$ . There is at most one such  $B$ , called the inverse of  $A$  and denoted by  $A^{-1}$ :

$$* \quad BA=I, \quad AC=I \Rightarrow B=C$$

$$(\because \quad B= B(AC) = (BA)C = C)$$

$$* \quad (A^{-1})^{-1} = A$$

$$* \quad A = \begin{bmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{bmatrix} \Rightarrow A^{-1} = \begin{bmatrix} \frac{1}{d_1} & & \\ & \ddots & \\ & & \frac{1}{d_n} \end{bmatrix}$$

$$* \quad (AB)^{-1} = B^{-1}A^{-1}$$

$$(\because \quad (AB)B^{-1}A^{-1} = ABB^{-1}A^{-1} = AA^{-1} = I$$

$$B^{-1}A^{-1}(AB) = B^{-1}A^{-1}AB = BB^{-1} = I$$

### Transposes

$$A = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 0 & 3 \end{bmatrix} \quad A^T = \begin{bmatrix} 2 & 0 \\ 1 & 0 \\ 4 & 3 \end{bmatrix}$$

$$\text{Def) } (A^T)_{ij} = A_{ji}$$

$$* \quad (AB)^T = B^T A^T$$

$$* \quad (A^{-1})^T = (A^T)^{-1}$$

$$\left( \because \quad (A A^{-1})^T = (A^T)^T A^T = I \right. \\ \left. \Rightarrow \quad (A^T)^{-1} = (A^{-1})^T \right)$$