

KECE470 Pattern Recognition

Chapter 3. Linear Classifiers

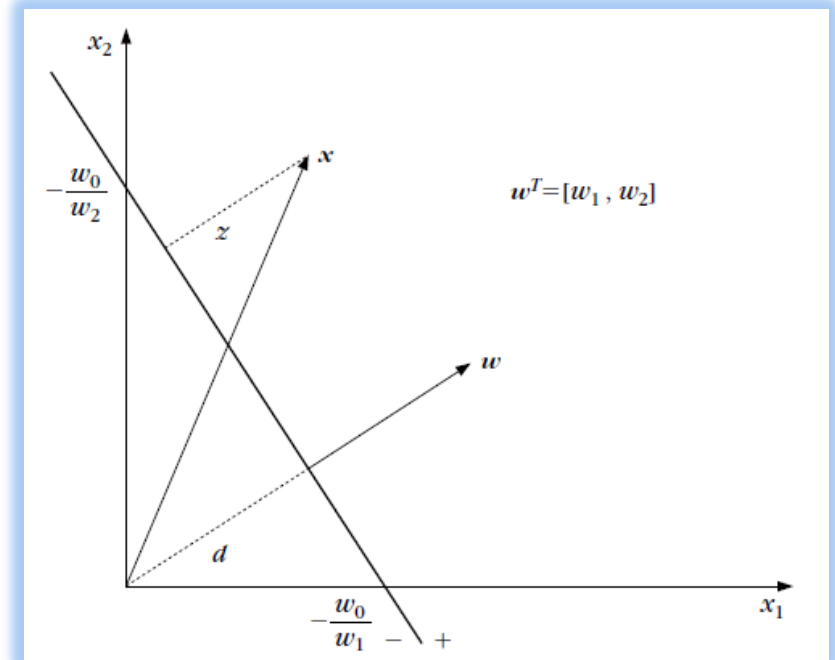
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Linear Classifiers

- Linear classifiers are simple and computationally attractive
- Linear discriminant functions → linear decision surfaces (decision hyperplanes)

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0 = 0$$

$$\Leftrightarrow \mathbf{w}^T (\mathbf{x} - \mathbf{x}_0) = 0$$



PERCEPTRON ALGORITHM

Linearly Separable Case

- There exists a hyperplane, $\mathbf{w}^{*T} \mathbf{x} = 0$, such that

$$\mathbf{w}^{*T} \mathbf{x} > 0 \quad \forall \mathbf{x} \in \omega_1$$

$$\mathbf{w}^{*T} \mathbf{x} < 0 \quad \forall \mathbf{x} \in \omega_2$$

- This formulation also covers the case of a hyperplane not crossing the origin, *i.e.*, $\mathbf{w}^{*T} \mathbf{x} + w_0^* = 0$, by defining the **extended** $(l + 1)$ -dimensional vectors

$$\mathbf{x}' \equiv [\mathbf{x}^T, 1]^T \quad \text{and} \quad \mathbf{w}' \equiv [\mathbf{w}^{*T}, w_0^*]^T.$$

- Then $\mathbf{w}^{*T} \mathbf{x} + w_0^* = \mathbf{w}'^T \mathbf{x}'$

Problem Formulation: Perceptron Cost

$$J(\mathbf{w}) = \sum_{\mathbf{x} \in Y} (\delta_x \mathbf{w}^T \mathbf{x})$$

- Y is the set of vectors, misclassified by the hyperplane \mathbf{w}
- The variable δ_x

$$\delta_x = \begin{cases} -1 & \text{if } x \in \omega_1 \\ +1 & \text{if } x \in \omega_2 \end{cases}$$

- For separating \mathbf{w} , $J(\mathbf{w}) = 0$ because $Y = \emptyset$
- $J(\mathbf{w})$ is continuous and piecewise linear

Optimization: Perceptron Algorithm

- Inspired by gradient descent

$$\mathbf{w}(t + 1) = \mathbf{w}(t) - \rho_t \left. \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \right|_{\mathbf{w}=\mathbf{w}(t)}$$

- Note that $\frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} = \sum_{\mathbf{x} \in Y} \delta_x \mathbf{x}$. Thus, we have

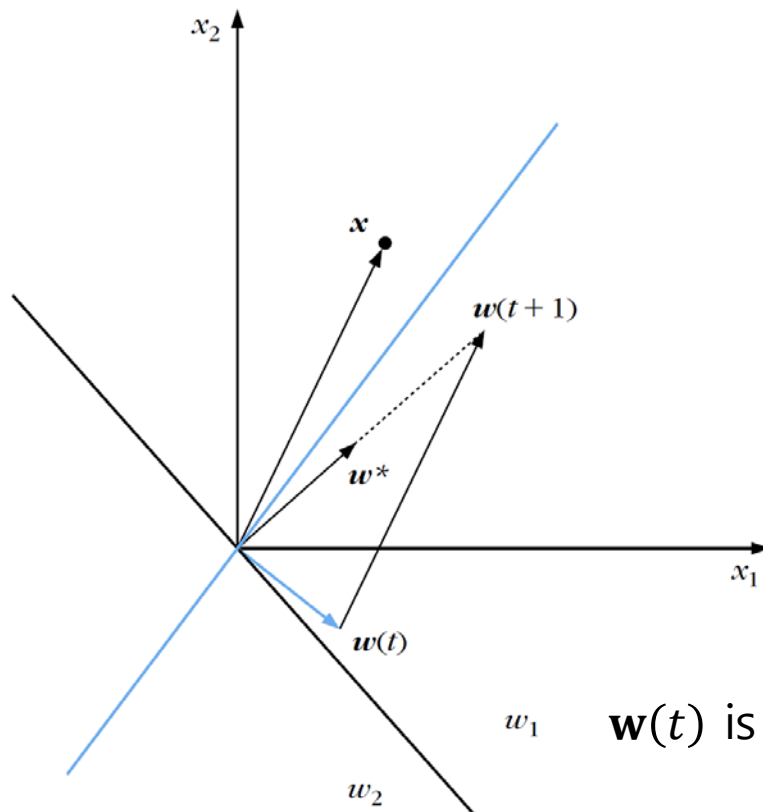
$$\mathbf{w}(t + 1) = \mathbf{w}(t) - \rho_t \sum_{\mathbf{x} \in Y} \delta_x \mathbf{x}$$

Perceptron Algorithm

- Choose $\mathbf{w}(0)$ randomly
- Choose ρ_0
- $t = 0$
- Repeat
 - $Y = \emptyset$
 - For $i = 1$ to N
 - If $\delta_{\mathbf{x}_i} \mathbf{w}(t)^T \mathbf{x}_i \geq 0$ then $Y = Y \cup \{\mathbf{x}_i\}$
 - End For
 - $\mathbf{w}(t + 1) = \mathbf{w}(t) - \rho_t \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} \Big|_{\mathbf{w}=\mathbf{w}(t)}$
 - Adjust ρ_t
 - $t = t + 1$
- Until $Y = \emptyset$

Perceptron Algorithm

- Remark
 - It converges to a solution in a finite number of steps, provided that $\rho_t \propto \frac{1}{t}$ (proof skipped)



w_1 $w(t)$ is updated to $w(t+1)$ to include x

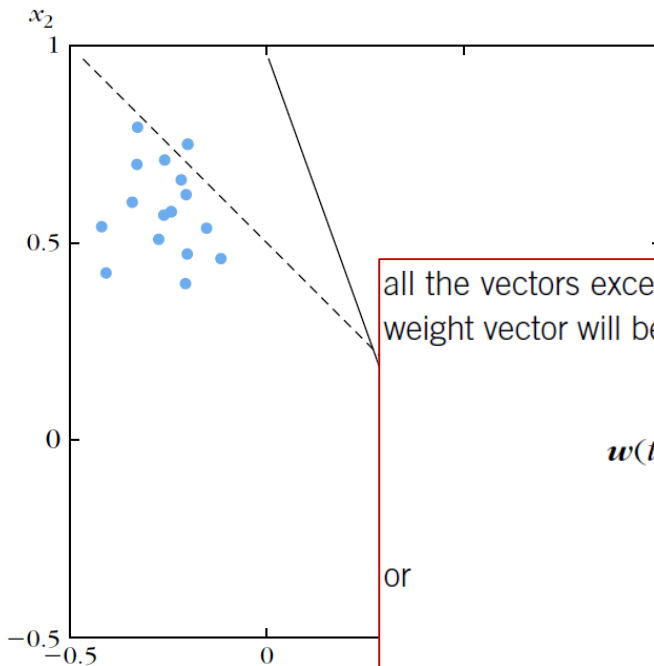
Perceptron Algorithm

Example 3.1

Figure 3.3 shows the dashed line

$$x_1 + x_2 - 0.5 = 0$$

corresponding to the weight vector $[1, 1, -0.5]^T$, which has been computed from the latest iteration step of the perceptron algorithm (3.9), with $\rho_t = \rho = 0.7$. The line classifies correctly



all the vectors except $[0.4, 0.05]^T$ and $[-0.20, 0.75]^T$. According to the algorithm, the next weight vector will be

$$\mathbf{w}(t+1) = \begin{bmatrix} 1 \\ 1 \\ -0.5 \end{bmatrix} - 0.7(-1) \begin{bmatrix} 0.4 \\ 0.05 \\ 1 \end{bmatrix} - 0.7(+1) \begin{bmatrix} -0.2 \\ 0.75 \\ 1 \end{bmatrix}$$

or

$$\mathbf{w}(t+1) = \begin{bmatrix} 1.42 \\ 0.51 \\ -0.5 \end{bmatrix}$$

FIGURE 3.3

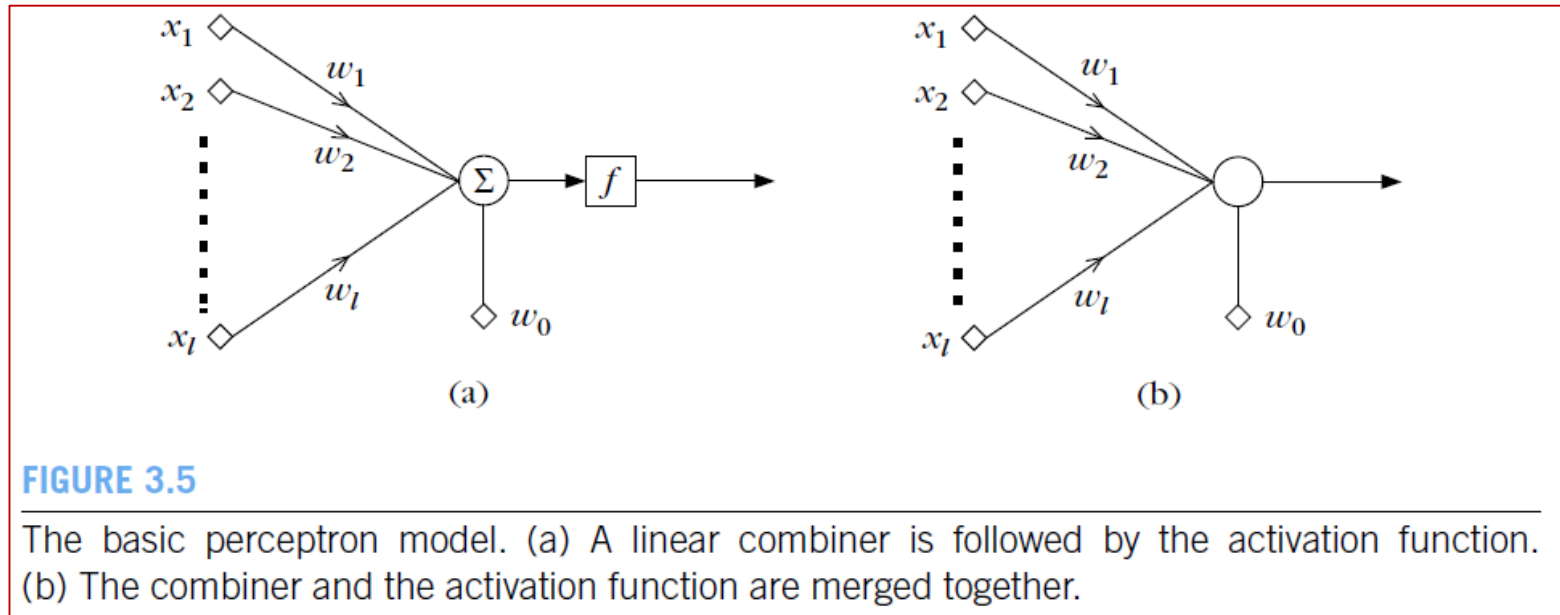
An example of the perceptron algorithm. After the line is turned from its initial location (dotted line) to the new position (solid line), all vectors are correctly classified.

The resulting new (solid) line $1.42x_1 + 0.51x_2 - 0.5 = 0$ classifies all vectors correctly, and the algorithm is terminated.

Terminology

If $\mathbf{w}^T \mathbf{x} + w_0 > 0$ assign \mathbf{x} to ω_1

If $\mathbf{w}^T \mathbf{x} + w_0 < 0$ assign \mathbf{x} to ω_2



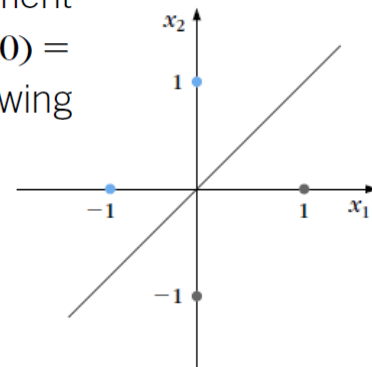
- **Perceptron** or **neuron**
- **Synaptic weights** or **synapses**
- **Activation function**: e.g. $f(x) = 2\delta(x) - 1$

Variants

- Reward and punishment schemes
 - Training vectors enter the algorithm cyclically
 - $\mathbf{w}(t + 1) = \mathbf{w}(t) + \rho \mathbf{x}_{(t)}$ if $\mathbf{x}_{(t)} \in \omega_1$ and $\mathbf{w}^T(t) \mathbf{x}_{(t)} \leq 0$
 - $\mathbf{w}(t + 1) = \mathbf{w}(t) - \rho \mathbf{x}_{(t)}$ if $\mathbf{x}_{(t)} \in \omega_2$ and $\mathbf{w}^T(t) \mathbf{x}_{(t)} \geq 0$
 - $\mathbf{w}(t + 1) = \mathbf{w}(t)$ otherwise

Example 3.2

Figure 3.4 shows four points in the two-dimensional space. Points $(-1, 0)$, $(0, 1)$ belong to class ω_1 , and points $(0, -1)$, $(1, 0)$ belong to class ω_2 . The goal of this example is to design a linear classifier using the perceptron algorithm in its reward and punishment form. The parameter ρ is set equal to one, and the initial weight vector is chosen as $\mathbf{w}(0) = [0, 0, 0]^T$ in the extended three-dimensional space. According to (3.21)–(3.23), the following computations are in order:



Variants

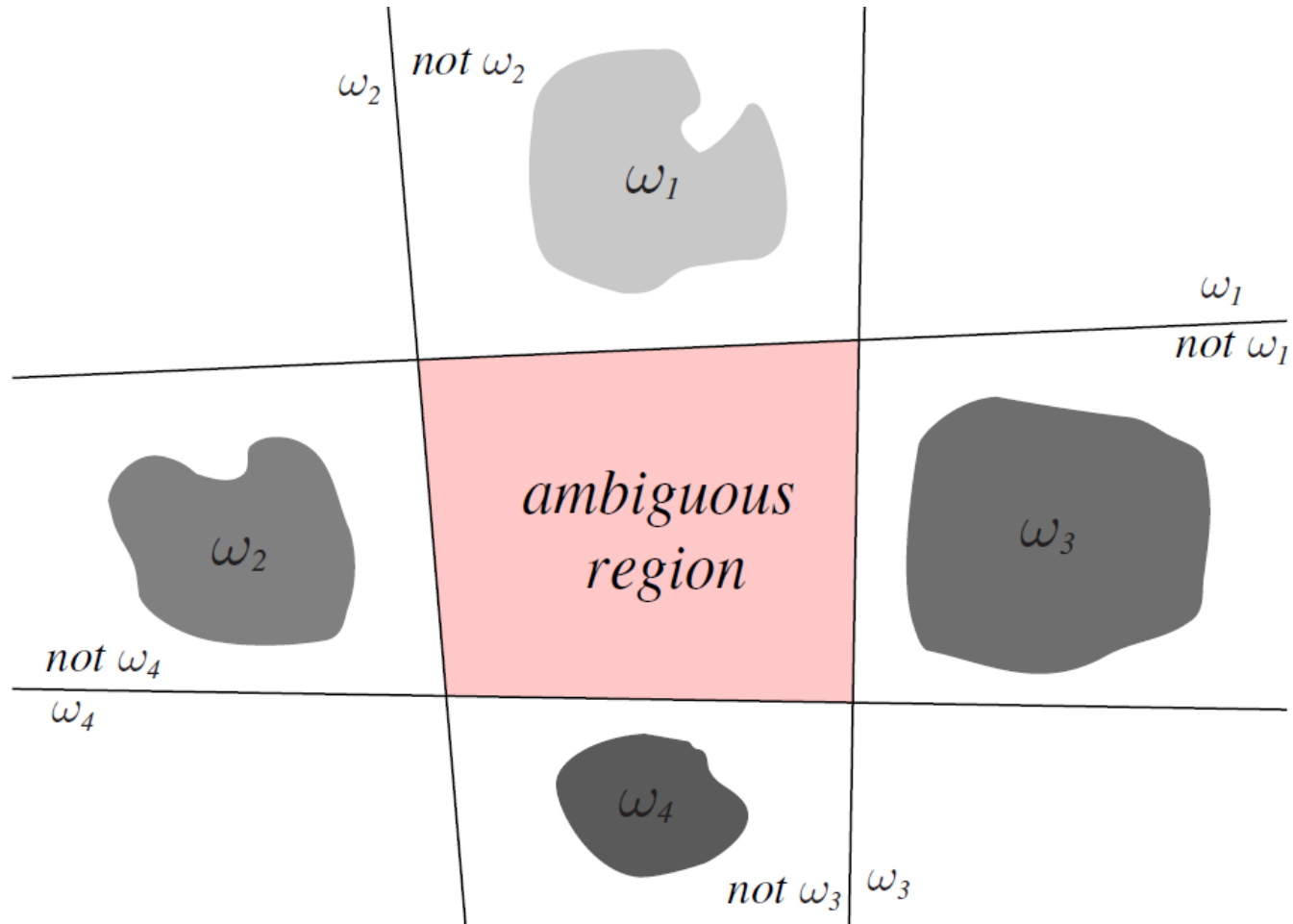
- Pocket Algorithm

- Converges to an optimal solution, even if not linearly separable

- Initialize the weight vector $\mathbf{w}(0)$ randomly. Define a stored (in the pocket!) vector \mathbf{w}_s . Set a history counter h_s of \mathbf{w}_s to zero.
- At the t -th iteration step, update $\mathbf{w}(t + 1)$ according to the perceptron rule. Use $\mathbf{w}(t + 1)$ to test the number h of training vectors correctly classified. If $h > h_s$ replace \mathbf{w}_s with $\mathbf{w}(t + 1)$ and h_s with h . Continue the iterations.

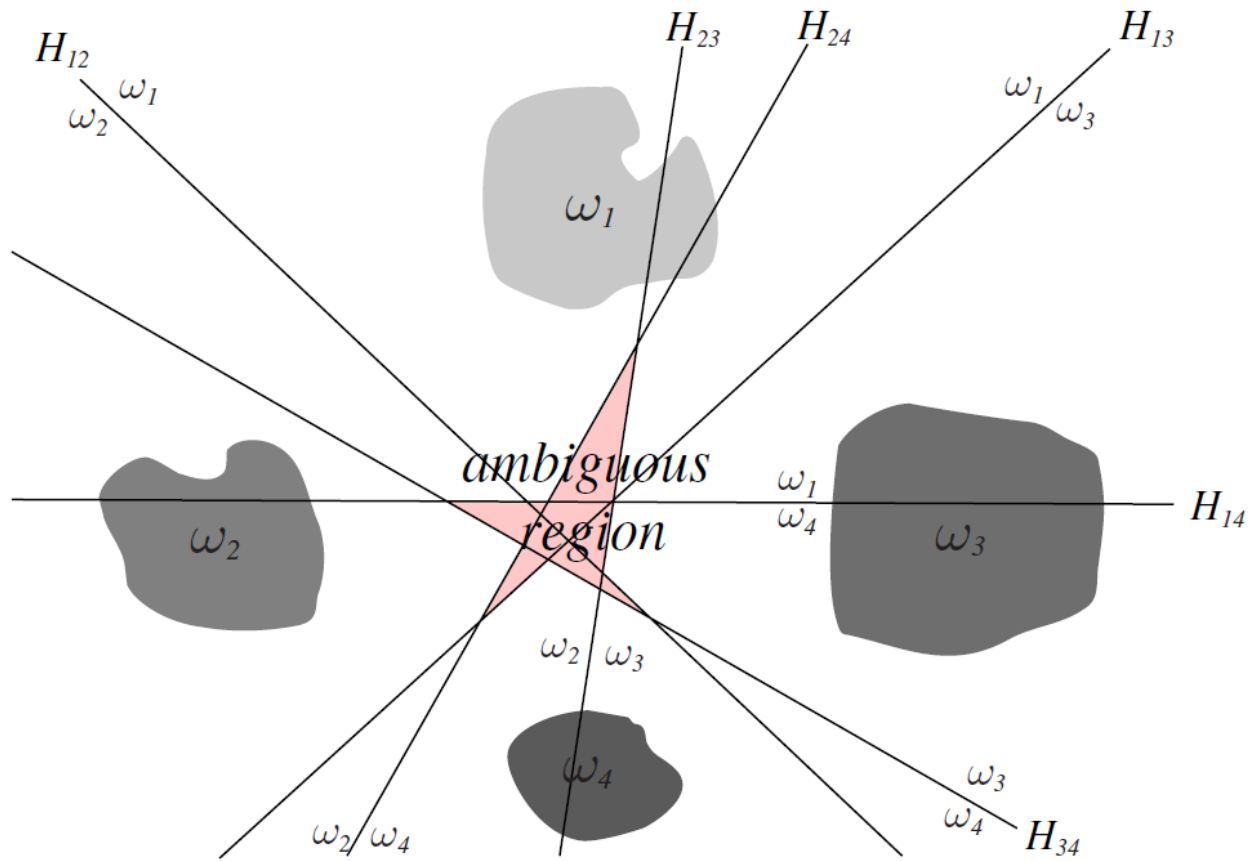
M-class Case

- Naïve approach I



M-class Case

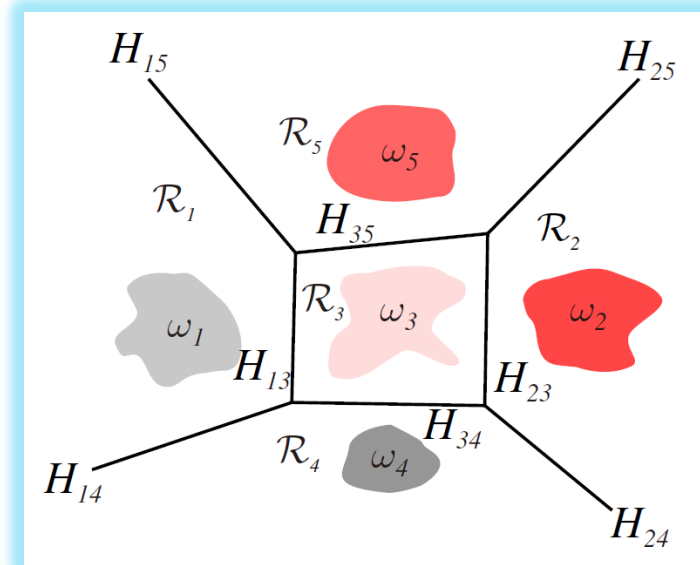
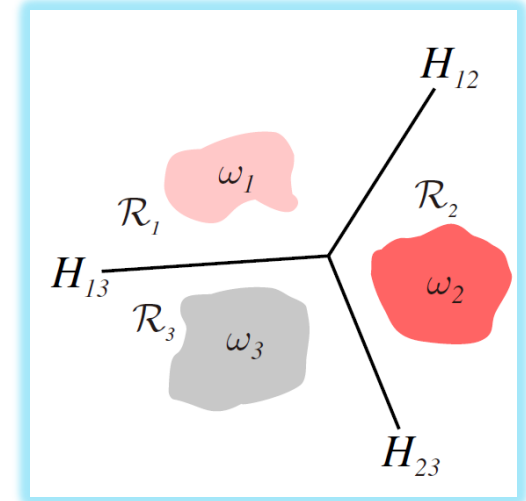
- Naïve approach II



M-class Case

- Linear Machine
 - Define M linear discriminant functions $g_i(\mathbf{x})$
 - Assign \mathbf{x} to ω_i if $g_i(\mathbf{x}) \geq g_j(\mathbf{x})$ for all j
- If R_i and R_j are contiguous, the boundary is given by the hyperplane

$$g_i(\mathbf{x}) = g_j(\mathbf{x})$$



Kesler's Construction

- Generalization to M -class task
 - Define a linear discriminant function \mathbf{w}_i , $i = 1, 2, \dots, M$, for each class. Classify a feature vector \mathbf{x} into class ω_i if

$$\mathbf{w}_i^T \mathbf{x} > \mathbf{w}_j^T \mathbf{x}, \forall j \neq i$$

- For each training vector from class ω_i , construct $M - 1$ vectors $\mathbf{x}_{ij} = [0^T, 0^T, \dots, \mathbf{x}^T, \dots, -\mathbf{x}^T, \dots, 0^T]^T$. It is a block vector, having zeros everywhere except at the i th and j th block positions, where it has \mathbf{x} and $-\mathbf{x}$, respectively.
- Also construct the block vector $\mathbf{w} = [\mathbf{w}_1^T, \dots, \mathbf{w}_M^T]^T$.
- If $\mathbf{x} \in \omega_i$, this imposes the requirement that $\mathbf{w}^T \mathbf{x}_{ij} > 0, \forall j \neq i$.
- The task now is to design a linear classifier, in the extended space, so that each extended training vector lies in its positive side.