

# Linear Algebra

## Chap. I Matrices and Gaussian Elimination

### Elimination

\* Gaussian Elimination: an example.

Suppose that we are given a system of equations

$$\begin{cases} 2u + v + w = 5 & \dots (1) \\ 4u - 6v = -2 & \dots (2) \\ -2u + 7v + 2w = 9 & \dots (3) \end{cases}$$

forward

elimination  $\Downarrow$  eliminating  $u$  from (2) and (3)

$$\begin{cases} 2u + v + w = 5 & \dots (1) \\ -8v - 2w = -12 & \dots (2') \quad (= (2) - 2 \times (1)) \\ 8v + 3w = 14 & \dots (3') \quad (= (3) + (1)) \end{cases}$$

$\Downarrow$  eliminating  $v$  from (3')

$$\begin{cases} 2u + v + w = 5 & \dots (1) \\ -8v - 2w = -12 & \dots (2') \\ u = 2 & \dots (3'') \quad (= (3') + (2')) \end{cases}$$

back

substitution.

$$\begin{aligned} -8v = -12 + 2w = -8 & \Rightarrow v = 1 \\ 2u = 5 - v - w = 2 & \Rightarrow u = 1. \end{aligned}$$

Therefore, we have the solution

$$u = 1, v = 1, w = 2$$

The same system can be written as

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix},$$

and the elimination can be simply denoted by

$$\begin{bmatrix} 2 & 1 & 1 & 5 \\ 4 & -6 & 0 & -2 \\ -2 & 7 & 2 & 9 \end{bmatrix}$$

$\Downarrow$

$$\begin{bmatrix} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 8 & 3 & 14 \end{bmatrix}$$

$\Downarrow$  upper triangle

$$\begin{bmatrix} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

pivot elements

Note 1. Row exchanges are necessary in some cases.

$$\begin{aligned} u + v + w &= 3 \\ 2u + 3v + 5w &= 9 \\ 4u + 6v + 8w &= 18 \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 1 & 3 \\ 2 & 2 & 5 & 9 \\ 4 & 6 & 8 & 18 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 2 & 4 & 6 \end{bmatrix} \xrightarrow{\text{row exchange}} \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 3 & 3 \end{bmatrix}$$

After back-substitution,

$$\begin{aligned} w &= 1 \\ 2w &= 6 - 4w = 2 \Rightarrow v = 1 \\ u &= 3 - v - w = 1 \end{aligned}$$

Note 2. Some systems break down (singular case)

$$\begin{aligned} u + v + w &= 3 \\ 2u + 2v + 5w &= 9 \\ 4u + 4v + 8w &= 16 \quad (17) \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 1 & 3 \\ 2 & 2 & 5 & 9 \\ 4 & 4 & 8 & 16 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 4 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

only two pivots.

$$\begin{aligned} w &= 1 \\ u &= 3 - v - w = 2 - v \end{aligned}$$

$\therefore (u, v, w) = (2 - d, d, 1)$

There are infinitely many solutions

$$0 = 1 \quad (\text{inconsistent})$$

There is no solution

singular cases.

\* Cost of elimination

For simplicity, ignore the right hand sides.

$$\begin{bmatrix} x & x & x & x & x & x \\ 0 & x & x & x & x & x \\ 0 & 0 & x & x & x & x \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & x & x & x \end{bmatrix}$$

From 1st pivot, we need  $n^2 - n$  operations (x and -)  
From 2nd pivot, we need  $(n-1)^2 - (n-1)$  operations.  
...

In total, we need  $\sum_{k=1}^n (k^2 - k) \approx \frac{1}{3} n^3 = O(n^3)$

\* Cost of back-substitution

From the last row, 1 op  
and last row, 2 op  
...

1st row n op  
In total, we need  $\sum_{k=1}^n k \approx \frac{1}{2} n^2 = O(n^2)$ .

Too basic operations in Gaussian elimination

① Subtract a multiple of row  $j$  from row  $i$ .

$$\begin{aligned} 2u + v + w &= 5 \\ 4u - 6v &= -2 & \Rightarrow & \quad -2u + v + w = 5 \\ -2u + 7v + 2w &= 9 & & \quad -2u + 7v + 2w = 9 \end{aligned}$$

This can be represented by a matrix multiplication.

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix}$$

$$R \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -12 \\ 9 \end{bmatrix}$$

Or more compactly,

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ -12 \\ 9 \end{bmatrix}$$

In general,  $E_{ij}$  denotes the matrix which subtracts a multiple of row  $j$  from row  $i$ .

It has 1 on the diagonal  
-1 in row  $i$ , column  $j$   
0 otherwise.

Ex)  $E_{41} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix}$

② Exchange row  $i$  with row  $j$

$$\begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 2 & 4 & 6 \end{bmatrix} \xrightarrow[\text{row 2 with row 3}]{\text{exchange}} \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 3 & 3 \end{bmatrix}$$

This can also be represented by a matrix multiplication

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 0 & 3 & 3 \\ 0 & 2 & 4 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 3 & 3 \end{bmatrix}$$

In general,  $P_{ij}$  denotes the matrix which exchanges row  $i$  with row  $j$ .

It is obtained by exchanging rows  $i$  and  $j$  of the identity matrix

Ex)  $P_{23} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$



Inverses of elementary matrix and permutation matrix.

$$\textcircled{1} \quad [I_4]^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

Inverse of (subtracting  $\lambda$  x row 1 from row 4)

= Adding  $\lambda$  x row 1 to row 4.

$$\textcircled{2} \quad P_{ij}^{-1} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = P_{ij}$$

Inverse of (exchanging rows  $i$  and  $j$ )

= Exchanging rows  $i$  and  $j$ .

### Triangular Factorization $A = LU$

Let's consider the first example of Gaussian elimination, where row exchanges are not necessary.

$$Ax = \begin{bmatrix} 1 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix} = b.$$

Ignoring the right-hand sides, we observe

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

$$\Downarrow A^{(1)} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -8 & -2 \\ -2 & 7 & 2 \end{bmatrix} = E_{\alpha} A \quad \text{where } E_{\alpha} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Downarrow A^{(2)} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 8 & 3 \end{bmatrix} = E_{\beta} A^{(1)} \quad \text{where } E_{\beta} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\Downarrow A^{(3)} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} = E_{\gamma} A^{(2)} \quad \text{where } E_{\gamma} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$A^{(3)} = U$  (upper triangular matrix)

$$= E_{\gamma} E_{\beta} E_{\alpha} A.$$

$$\Rightarrow A = (E_{\gamma} E_{\beta} E_{\alpha})^{-1} U$$

$$= E_{\alpha}^{-1} E_{\beta}^{-1} E_{\gamma}^{-1} U$$

Note that

$$E_{\alpha}^{-1} E_{\beta}^{-1} E_{\gamma}^{-1} = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \\ = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \\ = L \quad (\text{lower triangular matrix})$$

Therefore

$$A = LU.$$

The factorization makes the computation of

$$Ax = b \quad \text{easier.}$$

$$LUz = b$$

$$Ux = c \Rightarrow \boxed{Lc = b}$$

$$\begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ 9 \end{bmatrix}$$

$$c_1 = 5, \quad c_2 = -2 - 2c_1 = -12$$

$$c_3 = 9 + c_1 + c_2 = 2.$$

// Solve triangular system 1

$$\boxed{Ux = c}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ & -8 & -2 \\ & & 1 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 5 \\ -12 \\ 2 \end{bmatrix}$$

$$w = 2, \quad -8v - 4 = -12 \rightarrow v = 1 \\ 2u + 1 + 2 = 5 \rightarrow u = 1$$

// Solve triangular system 2

Remarks

① The above example shows how we solve  $Ax = b$  in practice, i.e.,

via Gaussian elimination or LU factorization. We don't first compute  $A^{-1}$  and then

$x = A^{-1}b$ , which is much more complicated.

② If row exchanges are necessary, we carry out them first to obtain  $A' = PA$  and obtain the factorization

$$PA = LU$$

Ex)  $PA = LU$

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 2 & 3 & 4 \end{bmatrix}$$

$$P_{1,2}A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 2 & 3 & 4 \end{bmatrix} \xrightarrow{E_{31}^{(2)}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 3 & 2 \end{bmatrix}$$

$$\xrightarrow{E_{32}^{(3)}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

$$\therefore E_{32}^{(3)} E_{31}^{(2)} P_{1,2}A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix} = U$$

$$P_{1,2}A = \begin{bmatrix} E_{31}^{(2)} \\ E_{32}^{(3)} \end{bmatrix}^{-1} \begin{bmatrix} I \\ I \end{bmatrix}^{-1} U$$

$$= \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix}^{-1} U$$

$$= \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} U$$

$$\therefore \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

## Gauss - Jordan Method to find $A^{-1}$

\* If a matrix  $A$  is non-singular (invertible),

We can make it diagonal using elementary matrices and permutation matrices. For example

$$E_4 P_2 E_1 P_1 E_1 E_1 A = D = \begin{bmatrix} d_1 & & \\ & d_2 & \\ & & \dots \\ & & & d_n \end{bmatrix}$$

Then,

$$D^{-1} E_4 P_2 E_1 P_1 E_1 E_1 A = I.$$

Therefore

$$A^{-1} = D^{-1} E_4 P_2 E_1 P_1 E_1 E_1.$$

If we start the forward elimination with

$$[A \ I],$$

the result is

$$D^{-1} E_4 P_2 E_1 P_1 E_1 E_1 [A \ I]$$

$$= [I \ A^{-1}].$$

To summarize, carry out the elimination

with  $[A \ I]$  to make the identity in the left side, i.e.  $[I \ B]$ .

Then  $B$  is the inverse of  $A$ .

Example)

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 4 & -6 & 0 & 0 \\ -1 & 7 & 2 & 0 \\ 2 & 0 & 0 & 1 \end{bmatrix}$$

$$\Downarrow \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 4 & -6 & 0 & 0 & 1 & 0 \\ -1 & 7 & 2 & 0 & 0 & 1 \\ 2 & 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

$$\Downarrow \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & -2 & 1 & 0 \\ 0 & 8 & 3 & 1 & 0 & 1 \end{bmatrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & -8 & -2 & \frac{3}{8} & 0 \\ 0 & -8 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & 0 & 0 & \frac{3}{8} & -\frac{2}{8} \\ 0 & -8 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$$

$$\Downarrow \begin{bmatrix} 1 & 0 & 0 & 0 & \frac{3}{8} & -\frac{2}{8} \\ 0 & 1 & 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 1 & -1 & 1 \end{bmatrix}$$

$$\therefore A^{-1} = \begin{bmatrix} \frac{3}{8} & -\frac{2}{8} & -\frac{3}{8} & -\frac{2}{8} \\ \frac{1}{8} & -\frac{1}{8} & -\frac{1}{8} & -\frac{1}{8} \\ \frac{1}{8} & -\frac{1}{8} & -\frac{1}{8} & -\frac{1}{8} \\ -1 & 1 & 1 & 1 \end{bmatrix}$$

### Exercise

8. Consider  $A$  a symmetric  $2 \times 2$  matrix  $B$  such that  $AB=I$  and  $BA=I$ . Then  $A$  is of rank one and  $B$ , which has rank of 1 and defined by  $AB=I$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\left( \forall \begin{bmatrix} x & y \end{bmatrix} \in \mathbb{R}^2 \right) \quad B \cdot (ABx) = (BA)Bx = x$$

$$A \cdot (BAy) = A \cdot y = y$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A \cdot (BAy) = Ay = y$$

$$\left( \forall \begin{bmatrix} x & y \end{bmatrix} \in \mathbb{R}^2 \right) \quad (AB)B^T x = A(BB^T)x = A(B^T x) = A \cdot \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix}$$

$$B \cdot (AB) = (BA)B = B \cdot B = B$$

### Homework

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Def: } (Bx)_i = B_{ij} x_j$$

$$A \cdot (BAx) = A^T A^T x$$

$$A \cdot (BAx) = (A^T)^T x$$

$$\left( \forall \begin{bmatrix} x & y & z & w \end{bmatrix} \in \mathbb{R}^4 \right) \quad (BA)A^T x = (BA) \cdot \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$