## Data Compression

## 2D Transforms

## Chang-Su Kim

## 2D Separable Transforms



- $Y=A U$ and $V=Y A^{\top}$, therefore $V=A U A^{\top}$
- $U=A^{-1} V\left(A^{\top}\right)^{-1}$
- If $A$ is unitary, then $A^{-1}=A^{H}$
- $U=A^{H} V\left(A^{H}\right)^{\top}$
- If $A$ is unitary and real (orthogonal), then
- U=A ${ }^{\top} V A$
- $\quad B^{i, j}=(i, j)$ th basis image $=b_{i} b_{j}^{\top}$


## DFT

1D basis vectors
(real, imaginary)






2D basis images (real, imaginary)

phase

shifted magnitude

## DCT

## 1D basis vectors



2D basis images


## Hadamard Transform

1D transform matrix
$H_{2}=\frac{1}{2}\left[\begin{array}{rrrr}1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1\end{array}\right]$
$\tilde{H}_{2}=\frac{1}{2}\left[\begin{array}{rrrr}1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \\ 1 & -1 & 1 & -1\end{array}\right]$
1D basis vectors
for 16-point Hadamard transform


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2D basis images


## Haar Transform



