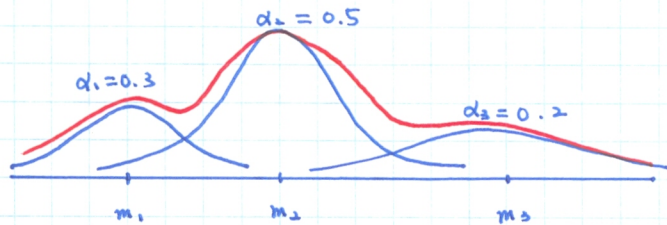


EM algorithm for parameter estimation of Gaussian mixture models

• Gaussian mixture

Example: a mixture of three Gaussian pdf



Component i is selected with prob. d_i
and then x is generated $\sim N(m_i, b_i^2)$

The mixture is parameterized by

$$\theta = (d_1, d_2, d_3, m_1, m_2, m_3, b_1^2, b_2^2, b_3^2)$$

$$\begin{aligned} P(x | \theta) &= \sum_{i=1}^3 d_i P_{N(m_i, b_i^2)}(x) \\ &= \sum_{i=1}^3 d_i \frac{1}{\sqrt{2\pi} b_i} \exp\left[-\frac{(x - m_i)^2}{2b_i^2}\right] \end{aligned}$$

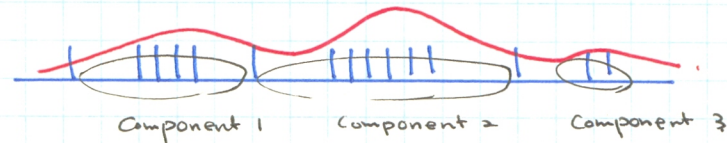
• Objective:

Given observed data x_1, x_2, \dots, x_N ,

Find θ which maximizes

$$\prod_{i=1}^N P(x_i | \theta) \quad \text{'' likelihood of } \theta.$$

Such θ is called the ML estimate.



• Missing data y_i (this is the segmentation result)

$y_i = k$ means that x_i comes from component k .

• ML estimate of θ when y_i 's are known.

$$S_1 = \{x_i | y_i = 1\} \quad S_2 = \{x_i | y_i = 2\} \quad S_3 = \{x_i | y_i = 3\}$$

$$d_k = \frac{|S_k|}{N}$$

$$m_k = \frac{1}{|S_k|} \sum_{x_i \in S_k} x_i$$

$$b_k^2 = \frac{1}{|S_k|} \sum_{x_i \in S_k} (x_i - m_k)^2$$

• EM algorithm

(It attempts to obtain the ML estimate of θ when y_i 's are unknown, and reaches a local maximum of the likelihood)

- It starts with an estimated θ and updates it to θ'

$$\alpha_k' = \frac{1}{N} \sum_{i=1}^N P(y_i = k | x_i, \theta) \quad \dots \textcircled{1}$$

Meaning of $p(y_i = k | x_i, \theta)$

= the probability that x_i comes from component k when θ is given.

Computation of $p(y_i = k | x_i, \theta)$

$$= \frac{P(y_i = k, x_i | \theta)}{P(x_i | \theta)} = \frac{P(y_i = k, x_i | \theta)}{\sum_{j=1}^3 P(y_i = j, x_i | \theta)}$$

$$= \frac{\alpha_k P_N(\mu_k, \sigma_k^2)(x_i)}{\sum_{j=1}^3 \alpha_j P_N(\mu_j, \sigma_j^2)(x_i)}$$

$P(y_i = 1 x_i, \theta)$	0.9	0.8	0.7	0.2	0.1	$\alpha_1' = \frac{0.9+0.8+0.7+0.2+0.1}{5}$
	x_1	x_2	x_3	x_4	x_5	
$P(2 ,)$	0.05	0.1	0.2	0.9	0.1	$\alpha_2' = \frac{0.05+0.15+0.2+0.9}{5}$
$P(3 ,)$	0.05	0.05	0.1	0.1	0.8	$\alpha_3' = \frac{0.05+0.05+0.1+0.1+0.8}{5}$

$$\mu_k' = \frac{\sum_{i=1}^N x_i P(y_i = k | x_i, \theta)}{\sum_{i=1}^N P(y_i = k | x_i, \theta)}$$

$$(b_k')' = \frac{\sum_{i=1}^N (x_i - \mu_k')^2 P(y_i = k | x_i, \theta)}{\sum_{i=1}^N P(y_i = k | x_i, \theta)} \quad \dots \textcircled{2}$$

After the estimation of θ ,

x_i is declared to come from component k

if $P(y_i = k | x_i, \theta) \geq P(y_i = l | x_i, \theta)$ for all l .

• Generalization of $\textcircled{1}$ and $\textcircled{2}$ to d -dimensional space

$$\alpha_k' = \frac{1}{N} \sum_{i=1}^N P(y_i = k | x_i, \theta)$$

d-dimensional vector

$$\mu_k' = \frac{\sum_{i=1}^N x_i P(y_i = k | x_i, \theta)}{\sum_{i=1}^N P(y_i = k | x_i, \theta)}$$

mean vector

$$\Sigma_k' = \frac{\sum_{i=1}^N (x_i - \mu_k') (x_i - \mu_k')^T P(y_i = k | x_i, \theta)}{\sum_{i=1}^N P(y_i = k | x_i, \theta)}$$

Covariance matrix

Note.

$$N(\mu, \Sigma) = \frac{1}{(2\pi)^{\frac{d}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1} (x-\mu)\right)$$